

Homework II

1

1 L and N clearly span the plane orthogonal to that spanned by M and \bar{M} . Thus, we only need to check

$$L \cdot L = \frac{1}{2}(T \cdot T + 2T \cdot Z + Z \cdot Z) = \frac{1}{2}(-1 + 0 + 1) = 0$$

$$N \cdot N = \frac{1}{2}(-1 + 1) = 0 \quad L \cdot N = \frac{1}{2}(-1 - 1) = -1$$

$$M \cdot M = \frac{1}{2}(X \cdot X + 2iX \cdot Y - Y \cdot Y) = \frac{1}{2}(1 + 0 - 1) = 0$$

$$\bar{M} \cdot \bar{M} = \frac{1}{2}(1 - 1) = 0 \quad M \cdot \bar{M} = \frac{1}{2}(1 - i^2) = 1$$

2 Let's solve problem 7.14 from d'Inverno's book first. We have

$$\begin{aligned} \nabla_a \nabla_b X_c &= \nabla_b \nabla_a X_c + R_{abc}{}^d X_d \\ &= -\nabla_b \nabla_c X_a + R_{abc}{}^d X_d \end{aligned}$$

We have used the definition of the curvature in the first line, and Killing's equation $\nabla_{[a} X_{b]} = 0$ in the second. The result has a cyclic permutation of indices, so we find

$$\begin{aligned} \nabla_a \nabla_b X_c &= -(-\nabla_c \nabla_a X_b + R_{bca}{}^d X_d) + R_{abc}{}^d X_d \\ &= \nabla_c \nabla_a X_b + (R_{abc}{}^d - R_{bca}{}^d) X_d \\ &= -\nabla_a \nabla_b X_c + (R_{abc}{}^d - R_{bca}{}^d + R_{cab}{}^d) X_d \end{aligned}$$

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Using the first Bianchi identity $R_{[abc]d} = 0$ and collecting the derivatives on the left gives the final result

$$\nabla_a \nabla_b X_c = R_{cba}{}^d X_d$$

when we divide by 2 and interchange the first two indices on the curvature.

When spacetime is flat, the right side here vanishes, so

$$\nabla_a \nabla_b X_c = 0 \Rightarrow \nabla_b X_c = w_{bc} = \text{const.}$$

Since $\nabla_{[cb} X_c] = 0$ by Killing's equation, w_{bc} must be anti-symmetric. Integrating again gives the result

$$X_c = X^b w_{bc} + t_c.$$

In n dimensions, w_{bc} has $\frac{1}{2}n(n-1)$ independent components, while t_c has n . Therefore, a Killing vector is specified by $\frac{1}{2}n(n+1)$ constants. In four dimensions, these ten constants describe four translations, three rotations and three boosts.

3 The unit basis vectors in the rotating frame rotate with the frame, so, for example

$$\frac{d}{dt} \hat{1}' = \vec{\omega} \times \hat{1}'$$

In the rotating frame, however, we take these to be constant. Thus,

$$\left[\frac{d\vec{v}}{dt} \right]_{s'} = \frac{dv_1}{dt} \hat{i}' + \frac{dv_2}{dt} \hat{j}' + \frac{dv_3}{dt} \hat{k}'$$

The result follows immediately by the Leibniz rule for the products $v_i \hat{i}'$, etc.

- 4 Let's take a different approach here. Using components in both frames, we write

$$r^\alpha \hat{e}_\alpha = s^\alpha \hat{e}_\alpha + r'^\alpha \hat{e}'_\alpha$$

Taking two derivatives, and recalling that $\dot{\hat{e}}_\alpha = 0$ and $\dot{\hat{e}}'_\alpha = \vec{\omega} \times \hat{e}'_\alpha$, we find

$$\begin{aligned} \ddot{r}^\alpha \hat{e}_\alpha &= \ddot{s}^\alpha \hat{e}_\alpha + \ddot{r}'^\alpha \hat{e}'_\alpha + 2 \dot{r}'^\alpha \dot{\hat{e}}'_\alpha + r'^\alpha \ddot{\hat{e}}'_\alpha \\ &= \ddot{s}^\alpha \hat{e}_\alpha + \ddot{r}'^\alpha \hat{e}'_\alpha + 2 \dot{r}'^\alpha \vec{\omega} \times \hat{e}'_\alpha \\ &\quad + r'^\alpha \frac{d}{dt} (\vec{\omega} \times \hat{e}'_\alpha) \end{aligned}$$

The result follows when we set $\vec{r}' = r'^\alpha \hat{e}'_\alpha$, $\dot{\vec{r}}' = \dot{r}'^\alpha \hat{e}'_\alpha$ and $\ddot{\vec{r}}' = \ddot{r}'^\alpha \hat{e}'_\alpha$, and recall that $\ddot{r}^\alpha = F^\alpha/m$ in the inertial frame.

- 5 The simplest generalization uses the torsion-free connection ∇_a :

$$\nabla_a F_{bc} = 0$$

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This is because the inertial coordinate connection ∂_a in Minkowski spacetime is the symmetric metric connection.

Now, using the Christoffel tensor Γ_{ab}^c for $\nabla_a = \partial_a$, where ∂_a is any coordinate derivative on curved spacetime, we find

$$\begin{aligned}\nabla_a F_{bc} &= \partial_a F_{bc} + \Gamma_{ab}^m F_{mc} + \Gamma_{ac}^m F_{bm} \\ &= \partial_a F_{bc} - 2\Gamma_{a[b}^m F_{c]m}\end{aligned}$$

We have used anti-symmetry of F_{ab} in the second line. When we anti-symmetrize over a as well, however, this second term vanishes because ∇_a is torsion-free and thus $\Gamma_{ab}^c = \Gamma_{ba}^c$. Therefore,

$$\partial_{[a} F_{bc]} = \nabla_{[a} F_{bc]} = 0$$

Thus, the coordinate curl of F_{bc} vanishes in all charts in all spacetimes.